

## Robot Vision: Second International Workshop, RobVis 2008, Auckland, New Zealand, February 18-20, 2008, Proceedings (Lecture Notes in Computer Science)



In 1986, B.K.P. Horn published a book entitled Robot Vision, which actually discussed a wider field of subjects, basically addressing the field of computer vision, but introducing robot vision as a technical term. Since then, the interaction between computer vision and research on mobile systems (often called robots, e.g., in an industrial context, but also including vehicles, such as cars, wheelchairs, tower cranes, and so forth) established a diverse area of research, today known as robot vision. Robot vision (or, more general, robotics) is a fast-growing discipline, already taught as a dedicated teaching program at university level. The term robot vision addresses any autonomous behavior of a technical system supported by visual sensoric information. While robot vision focusses on the vision process, visual robotics is more directed toward control and automatization. In practice, however, both fields strongly interact. Robot Vision 2008 was the second international workshop, counting a 2001 workshop with identical name as the first in this series. Both workshops were organized in close cooperation between researchers from New Zealand and Germany, and took place at The University of Auckland, New Zealand. Participants of the 2008 workshop came from Europe, USA, South America, the Middle East, the Far East, Australia, and of course from New Zealand.

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**Iterative Low Complexity Factorization for Projective Reconstruction** Jun 4, 2017 List of computer science publications by BibTeX records: Heiko Hirschmuller. title = {Special issue on robot vision: what is robot vision?}, journal = {J. booktitle = {2nd International Conference on 3D Vision, 3DV 2014, Tokyo, .. Workshop, RobVis 2008, Auckland, New Zealand, February 18-20, 2008, **Robot Vision: Second International Workshop, RobVis 2008** Robot Vision: Second International Workshop, RobVis 2008, Auckland, New Zealand, February 18-20, 2008, Proceedings (Lecture Notes in Computer Science) **Robot Vision - Springer** Robot Vision. Volume 4931 of the series Lecture Notes in Computer Science pp 207-218. Birds-Eye View Vision System for Vehicle Surrounding Monitoring Surrounding Monitoring Book Title: Robot Vision Book Subtitle: Second International Workshop, RobVis 2008, Auckland, New Zealand, February 18-20, 2008. **Robot Vision: Second International Workshop - Google Books** Mar 28, 2008 Robot Vision: Second International Workshop, RobVis 2008, Auckland, New Zealand, February 18-20, 2008, Proceedings. by Gerald Sommer **Robot Vision, Gerald Sommer (Volume editor) Reinhard Klette** Robot Vision. Second International Workshop, RobVis 2008, Auckland, New Zealand, February 18-20, 2008. Proceedings. Editors. Gerald Sommer Reinhard Klette. Conference proceedings RobVis 2008 Part of the Lecture Notes in Computer Science book series (LNCS, volume 4931). Download book PDF. Papers **Lecture Notes in Computer Science 4931 - Springer Link** Sommer Reinhard Klette (Eds.) Robot Vision. Second International Workshop, RobVis 2008. Auckland, New Zealand, February 18-20, 2008. Proceedings. 1 3 **Robot Vision, Second International Workshop, RobVis 2008** Centre for Robotics & Vision Lectures & Talks International Workshop, RobVis 2008, Auckland, New Zealand, February 18-20, 2008, Proceedings series = Lecture Notes in Computer Science, title = Robot Vision, Second International **9783540781561: Robot Vision: Second International Workshop** Robot vision : second international workshop, RobVis 2008, Auckland, New Zealand, February 18-20, 2008 proceedings SpringerLINK Lecture Notes in Computer Science Contemporary (1997-present).